

C^∞ -HOMOGENEOUS CURVES ON ORIENTABLE CLOSED SURFACES

DONČO DIMOVSKI

UNIVERSITY OF SKOPJE, SKOPJE, YUGOSLAVIA

DUŠAN REPOVŠ

UNIVERSITY OF LJUBLJANA, LJUBLJANA, YUGOSLAVIA

EVGENIJ V. ŠČEPIN

STEKLOV MATHEMATICAL INSTITUTE, MOSCOW, USSR

Let M^2 be an oriented smooth closed surface. A Jordan curve on M^2 is a continuous map $K: [0, 1] \rightarrow M^2$ (or $K: \mathbb{R} \rightarrow M^2$) such that for each $t \in (0, 1)$ (or $t \in \mathbb{R}$) there is an $\varepsilon > 0$ such that K is one-to-one on the open ε -neighborhood of t . The orientation on a Jordan curve K on M^2 will always be the induced orientation by the chosen one on the surface M^2 .

A Jordan curve K on M^2 is said to be C^∞ -homogeneous in M^2 if for every two points $x, y \in K$ there exists a diffeomorphism $h_{x,y}: M^2 \rightarrow M^2$ such that (i) $h_{x,y}(x) = y$; (ii) $h_{x,y}(K) \subset K$; (iii) $h_{x,y}$ is orientation preserving for all x and y (or it is orientation reversing for all x and y); and (iv) $h_{x,y}$ preserves the orientation of K for all x and y (or it reverses the orientation of K for all x and y).

PROPOSITION 1. Let K be a C^∞ -homogeneous Jordan curve in the plane \mathbb{R}^2 . Then for every point $x \in K$ there exist a closed neighborhood $U \subset \mathbb{R}^2$ of x and smooth curves $C_1, C_2 \subset U$ such that (i) $K \cap U$ separates U ; (ii) C_1 and C_2 lie on the opposite sides of $K \cap U$; and (iii) $C_1 \cap K = \{x\} = C_2 \cap K$ (i.e. x is wedged between C_1 and C_2).

Proof. Let $x \in K$. Since K is C^∞ -homogeneous Jordan curve in \mathbb{R}^2 the Jordan Curve Theorem implies that there is a closed neighborhood $U \subset \mathbb{R}^2$ of x in \mathbb{R}^2 such that $K \cap U$ separates U . Let

$p_i \in U - K$, $i=1,2$, be any two points on the opposite sides of $K \cap U$. Let $p_i^* \in K$ be a point on K nearest to p_i , $i=1,2$ (there can be more than one, in general). Let C_i^* be a circle in R^2 centered at p_i^* with radius $d(p_i, p_i^*)$, $i=1,2$. Modify the circles C_i^* so that eventually $C_i^* \cap K = \{p_i^*\}$, $i=1,2$, while keeping them smooth at all points. Use the C^∞ -homogeneity of the curve K to produce two diffeomorphisms $h_i: R^2 \rightarrow R^2$ such that $h_i(p_i^*) = x$. Define C_i to be the component of $h_i(C_i^*)$ which contains the point x , $i=1,2$. It's now easy to verify that the curves C_1 and C_2 satisfy the required properties.

A 1-parameter group of diffeomorphisms of an oriented closed smooth surface M^2 is a continuous map $G: R \times M^2 \rightarrow M^2$ such that (i) $G(t, x) = g^t(x)$ where g^t is a diffeomorphism of M^2 ; (ii) $g^{t+s} = g^t g^s$; and (iii) $g^0 = id_{M^2}$. In other words, a 1-parameter group of diffeomorphisms is a homomorphism $G: (R, +) \rightarrow (Diff(M^2), \circ)$ such that $G: R \times M^2 \rightarrow M^2$ is continuous.

PROPOSITION 2. Let $G: R \times M^2 \rightarrow M^2$ be a 1-parameter group of diffeomorphisms of M^2 and let $x \in M^2$ be an arbitrary point of M^2 . Then the orbit $0_x = \{g^t(x) \mid t \in R\}$ is a C^∞ -homogeneous curve in M^2 unless x is a fixed point.

Proof. Any two diffeomorphisms g^t and g^s are homotopic via the map $G: [t, s] \times M^2 \rightarrow M^2$, $t < s$, which implies that either both of them preserve the orientation of M^2 or they both reverse it. The same holds for the orientation of the orbits. Pick $x \in M^2$ and let $y \in 0_x$. Then $H_y = \{t \mid g^t(y) = y\}$ is a subgroup of $(R, +)$ so there are 3 possibilities: H_y is either discrete or dense in R or trivial (i.e. 0). If H_y is dense in R it follows that $H_y = R$ hence $0_x = 0_y = \{x\} = \{y\}$. If $0_x \neq \{x\}$ and $H_x = \{0\}$ then 0_x is the image of an embedding of R in M^2 . If H_x is a discrete group, i.e. $H_x = rZ$ for some $r > 0$, then 0_x is the image of an embedding of $[0, r)$ in M^2 , i.e. of a map $f: [0, r) \rightarrow R$, $f(0) = f(r)$, and f one-to-one on the interval $[0, r)$.

For every two points $y, z \in 0_x$ there exist $t, s \in R$ such that $y = g^t(x)$ and $z = g^s(x)$. Consequently, $g^{s-t}(y) = g^{s-t}(g^t(x)) = g^s(x) = z$ hence g^{s-t} is a required diffeomorphism of M^2 since we also have that

$g^{s^{-t}}(0_x) = 0_x$. This proves that the orbit 0_x is indeed C^∞ -homogeneous in M^2 as asserted.

PROPOSITION 3. Let K be a Jordan curve in the plane R^2 and suppose that at a point $x \in K$, K is wedged between two smooth curves, i.e. that there are two smooth curves $C_1, C_2 \subset R^2$ such that $C_1 \cap K = C_2 \cap K = \{x\}$. Then K has a tangent at x .

Proof. Consider the secants $L_n \subset R^2$ of K based at x . For every $n \in \mathbb{N}$, pick $q_n \in L_n \cap K$. We may choose the sequence (q_n) so that it converges to x . There are two possible cases to consider.

Case 1. For all but finitely many n , $q_n \notin C_1 \cup C_2$. Then for some subsequence $(q_{s(n)})$, $L_{s(n)}$ have the same slope as the tangent to C_1 (and hence to C_2) at x and therefore so does the limit.

Case 2. For some subsequence $(q_{s(n)})$, $q_{s(n)} \in C_1$ (resp. C_2). Then $L_{s(n)}$ is also a secant for C_1 (resp. C_2) at x hence the slopes of $L_{s(n)}$ must converge - to the derivative of C_1 (resp. C_2) at x . This implies that K is differentiable at x .

EXAMPLE. The following example shows that in Proposition 3 one cannot, in general, also prove that the curve K has a continuous derivative at x (hence much less that K is smooth at x). Let $P_1 = \{(x, x^2) \mid x \in \mathbb{R}\} \subset R^2$ and $P_2 = \{(x, -x^2) \mid x \in \mathbb{R}\} \subset R^2$. For every $n \in \mathbb{N}$, let $A_n, A_n^* \in P_1$ and $B_n, B_n^* \in P_2$ be given by:

$$A_n = \{(2n)^{-1}, (4n^2)^{-1}\}, \quad A_n^* = \{-(2n)^{-1}, (4n^2)^{-1}\},$$

$$B_n = \{(2n-1)^{-1}, -(2n-1)^{-2}\}, \quad B_n^* = \{-(2n-1)^{-1}, -(2n-1)^{-2}\},$$

and let $K^* = \bigcup_{n \in \mathbb{N}} (\overline{A_n B_n} \cup \overline{A_n^* B_n^*} \cup \overline{A_n^* B_n} \cup \overline{A_n B_n^*}) \cup \{(0,0)\}$. Let K be the curve in the plane, obtained from K^* by smoothing its corners A_n, A_n^*, B_n, B_n^* (without changing K^* near the x -axis). Then the point $T = (0,0) \in K$ is wedged between the smooth curves P_1 and P_2 but the first derivative of K at T isn't continuous (hence, in particular, K isn't smooth at T). To see this, let $f: [-1,1] \rightarrow \mathbb{R}$ be the map whose graph is K and define the map $F = (f_1, f_2): [-1,1] \rightarrow R^2$ by $f_1(t) = t$ and $f_2(t) = f(t)$. Then $df_1/dt|_{(0)} = 1$ and $df_2/dt|_{(0)} = 0$. Let $(t_n) \subset \mathbb{R}$ be the sequence of points on the x -axis, defined by $F(t_n) = \overline{A_n B_n} \cap (x\text{-axis})$. Then $\lim t_n = 0$ whereas $\lim df_2/dt|_{(t_n)} = -2 \neq 0 = df_2/dt|_{(0)}$.

REMARK. The curve K constructed above isn't C^∞ -homogeneous in R^2 . For suppose this were the case and pick any point $T^* \neq T$ on K . We would then have a diffeomorphism $h: R^2 \rightarrow R^2$ such that $h(T) = T^*$. Now, K is clearly smooth at T^* hence it should also be smooth at the image of T^* , $h^{-1}(T^*) = T$. Contradiction.

QUESTION. Under the additional assumption in Proposition 3, that the curve K is C^∞ -homogeneous in R^2 , can one prove that K is then necessarily smooth at x , i.e. does " C^∞ -homogeneous" imply "smooth"? (Note that the converse is true, i.e. every smooth curve in R^2 is locally flat at every point hence one can build diffeomorphisms of R^2 which interchange arbitrary pairs of points on K .)

After this paper was written, W.J.R. Mitchell brought to our attention the work of L.D. Loveland²⁾ where he used a similar idea of wedging the curve or a sphere between balls: using entirely different methods from ours he proved e.g. that a curve $K \subset S^3$ is tame in S^3 (i.e. there is an ambient homeomorphism of S^3 which takes K onto a polygonal arc) if for some $t > 0$ at each $x \in K$ there are 3-dimensional balls $B_1, B_2 \subset S^3$, each with radius t , such that $B_1 \cap B_2 = (B_1 \cup B_2) \cap K = \{x\}$.

Our work, on the other hand, was inspired by a remark in V.I. Arnol'd's textbook¹⁾ (cf. Problem 1 on p.24). Note that our argument yields a very simple geometric proof of a special case of Theorem (5.2.3) in D. Montgomery-L. Zippin's monograph³⁾.

ACKNOWLEDGEMENTS. The authors wish to acknowledge comments from A. Gray. The second author wants to thank the Soviet Academy of Sciences for its support during his visit at the Steklov Mathematical Institute in Spring 1988 when this research was started. This project is supported in part by a grant from the Research Council of Slovenia.

R E F E R E N C E S

- (1) Arnol'd, V.I., "Ordinary Differential Equations"(Russian), Nauka, Moscow 1971.
- (2) Loveland, L.D., "Double tangent ball embeddings of curves in E^3 ", *Pacif. J. Math.* 104 (1983), 391-399.
- (3) Montgomery, D. and Zippin, L., "Topological Transformation Groups", Interscience Publ. Inc., New York 1955, Interscience Tracts in Pure and Appl. Math. No.1.