# ON CALCULATION OF THE WITTEN INVARIANTS OF 3-MANIFOLDS

## EUGENE RAFIKOV, DUŠAN REPOVŠ and FULVIA SPAGGIARI

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#### **Abstract**

In this paper we present a short definition of the Witten invariants of 3-manifolds. We also give simple proofs of invariance of those obtained for r=3 and r=4. Our definition is extracted from the 1993 paper of Lickorish and the Prasolov-Sossinsky book, where it is dispersed over 20 pages. We show by several examples that it is indeed convenient for calculations.

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#### 1. Definition of the Witten invariant

The construction of Witten invariants of 3-manifolds and the proof of their invariance use deep ideas from the quantum field theory and the theory of Temperley-Lieb algebras and are not short. But a mathematician might want to calculate and apply these invariants without necessarily understanding their origin. The definition of the Witten invariants in [6, page 660] is direct and short, but is not so convenient for calculations. In this paper we present a short definition of the Witten invariants (Theorem 1.3) which is extracted from [8] (where it is dispersed over 20 pages, mixed with the proof of invariance) and we show by several examples that it is indeed more convenient for calculations. In Section 2 we give a new simple proof of invariance for r = 4.

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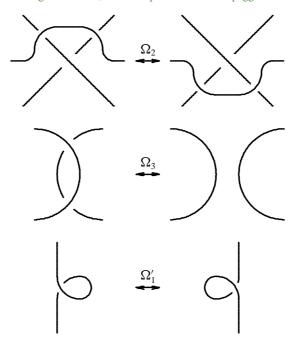


FIGURE 1.

The definition of the Witten invariant is based on the representation of 3-manifolds by (unoriented) plane diagrams. By a *plane diagram* we understand a set of circles in  $\mathbb{R}^2$  in general position, with chosen undercrossing and overcrossing at each intersection point. For every single component  $D_k$  of the plane diagram D we can determine its integer framing as follows. Choose any orientation of  $D_k$ . Define the framing as the sum of the signs  $(\pm 1)$  of all of its crossings. Note that this number is independent of the choice of orientation on  $D_k$ .

Suppose that L is an unoriented link in  $S^3$  and that an integer g(k) is assigned to each component  $L_k$  of L. Then the pair (L, g) is called a *framed link*. We say that a framed link (L, g) is represented by a plane diagram D, if D is a diagram for L in the usual sense and g(k) equals the framing of  $D_k$ , for every single component  $D_k$  of D.

It is well known that every closed oriented 3-manifold can be obtained from the 3-sphere  $S^3$  by the Dehn surgery on some framed link (L, g). Denote by  $\chi_D$  the 3-manifold obtained by the Dehn surgery along the framed unoriented link, corresponding to D.

**PROPOSITION** 1.1 ([3, 1]). Suppose that D and D' are plane diagrams. Then  $\chi_D \cong \chi_{D'}$  if and only if D' can be obtained from D by a sequence of the Reidemeister moves  $\Omega_1'$ ,  $\Omega_2$ , and  $\Omega_3$  shown in Figure 1 and the Fenn-Rourke moves shown in Figures 4 (a)–(b).

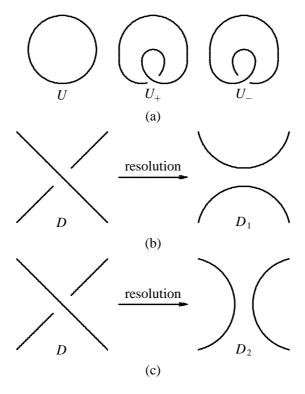


FIGURE 2.

For a plane diagram  $D=(D_1,\ldots,D_n)$ , consider any oriented link  $L=(L_1,\ldots,L_n)$  in  $S^3$ , whose plane projection coincides with D. Let  $b_{pq}=\operatorname{lk}(L_p,L_q)$  for  $p\neq q$  and let  $b_{kk}$  equal the framing of  $D_k$ . Denote by  $b_+(D)$  and  $b_-(D)$  the numbers of positive and negative eigenvalues of the linking coefficients matrix  $(b_{pq})$  of L. Let  $\sigma(D)=b_+(D)-b_-(D)$  be the signature of  $(b_{pq})$  and  $D\cdot D=\sum_{p,q}b_{pq}\pmod{4}$ . Clearly, the above numbers depend only on D, not on L and its orientation. We set  $\sigma=\sigma(D)$  and  $b_\pm=b_\pm(D)$  when D is fixed and no confusion can arise. Let |D| be the number of components in D. Then  $\operatorname{rk} H_1(\chi_D,\mathbb{Z})=|D|-b_+(D)-b_-(D)$ . Denote by #D the number of crossings in D. Let  $|D|_+$  and  $|D|_-$  be the numbers of the connected components after resolution of all the crossings as shown in Figures 2 (b) and (c), respectively.

In what follows capital Latin letters denote (unoriented) plane diagrams (in [8] they are sometimes called *framed diagrams*). Let  $U_+$ , U and  $U_-$  be the diagrams representing the unknot with framings +1,0 and -1, respectively (see Figure 2 (a)).

Everywhere below we suppose that diagrams in the equalities coincide except where shown in corresponding figures.

The *Kauffman bracket* is a function  $\langle \cdot \rangle$ : {plane diagrams}  $\to \mathbb{Z}[a^{\pm 1}]$ , defined by

the following three properties (see for example [8, Section 26, (1)-(3)]):

- (a)  $\langle D \rangle = a \langle D_1 \rangle + a^{-1} \langle D_2 \rangle$ , where the diagrams D,  $D_1$  and  $D_2$  are shown in Figures 2 (b)–(c);
- (b)  $\langle D \sqcup U \rangle = (-a^2 a^{-2})\langle D \rangle$ ; and
- (c)  $\langle \emptyset \rangle = 1$ .

The normalization of (c) is not entirely standard, but in this paper it is more convenient to use  $\langle D \rangle$  instead of the *original Kauffman bracket*  $\langle D \rangle/(-a^2-a^{-2})$ .

PROPOSITION 1.2 ([2, 5, 8, Section 26]). The Kauffman bracket is unchanged by the Reidemeister moves  $\Omega'_1$ ,  $\Omega_2$ , and  $\Omega_3$ .

THEOREM 1.3 ([8, 7, 27.3, 28.2] cf. [6]). Fix integers  $r \ge 3$  and k = 1, ..., 4r - 1 relatively prime to 2r. Define the polynomial

$$\omega(\alpha) = \prod_{\substack{l=1\\k\pm l \neq r, 3r}}^{r-1} \left(\alpha - 2\cos\frac{\pi l}{r}\right).$$

For a plane diagram D with n = |D| components, let  $D^{(k_1,\ldots,k_n)}$  be the diagram obtained from D by taking  $k_i$  curves, close and parallel to the i-th component. Define a polylinear map  $f_D: (\mathbb{C}[\alpha])^n \to \mathbb{C}$  on the basic elements by setting  $f_D(\alpha^{k_1},\ldots,\alpha^{k_n}) = \langle D^{(k_1,\ldots,k_n)} \rangle$  at  $a = \exp(\pi i k/2r)$ . Then the following number (the Witten invariant for r at a) depends only on the oriented  $\chi_D$ :

$$W(D) = f_{U_{\perp}}^{-b_{+}(D)}(\omega) \cdot f_{U_{-}}^{-b_{-}(D)}(\omega) \cdot f_{D}(\omega, \dots, \omega).$$

REMARK 1.4. It follows from [Lic93, Lemma 4] or [PrSo97, Proposition 29.4] that  $f_{U_+}(\omega) \neq 0$ . For r = 3 and r = 4, we easily verify it below.

REMARK 1.5. It is easier to calculate the polynomial  $\omega$  not by the explicit formula of Theorem 1.3 but by the following algorithm. Define the (renormalized Chebyshev) polynomials  $S_n(\alpha)$  by the recurrence formula  $S_0 = 1$ ,  $S_1 = \alpha$  and  $S_{n+1} = \alpha S_n - S_{n-1}$ . Then

$$\omega = (-1)^{r-k+1} \sum_{n=0}^{r-2} (-1)^n \frac{\sin(\pi k (n+1)/r)}{\sin(\pi k/r)} S_n.$$

Indeed, it suffices to show that the above sum has exactly r-2 roots  $2\cos(\pi l/r)$ , where  $1 \le l \le r-1$  and  $k \pm l \ne r$ , 3r (there are exactly r-2 numbers l with these

properties). Note that  $\sin x \cdot S_n(2\cos x) = \sin(n+1)x$ . Then

$$2\sin(\pi k/r)\sin(\pi l/r)\omega(2\cos(\pi l/r))$$

$$=2\sum_{n=0}^{r-2}(-1)^n\sin(\pi k(n+1)/r)\sin(\pi l(n+1)/r)$$

$$=\sum_{n=1}^{r-1}(-1)^{n+1}\cos(\pi (k+l)n/r)-\sum_{n=1}^{r-1}(-1)^{n+1}\cos(\pi (k-l)n/r)$$

$$=(-1)^{r+k+l}-(-1)^{r+k-l}=0.$$

REMARK 1.6. For odd r in Theorem 1.3, one can also take  $k=1,\ldots,2r-1$  relatively prime to 2r,  $a=e^{\pi i k/r}$  and

$$\omega(\alpha) = \prod_{\substack{l=1\\2k \pm l \neq r, 3r}}^{r-1} \left(\alpha - 2\cos\frac{\pi l}{r}\right).$$

EXAMPLE 1.7.  $W(S^3) = W(U_{\pm}) = 1$ .

EXAMPLE 1.8. It follows from [9, 3.4] that a changing of the orientation of 3-manifold has the effect of complex conjugation on the Witten invariants.

EXAMPLE 1.9. For  $a = e^{\pi i/3}$ , we have  $\langle D \rangle = 1$ . This can be verified by induction on the number of crossings in D using the definition of the Kauffman bracket.

EXAMPLE 1.10. Suppose r=3, k=1 and  $a=e^{\pi i/3}$ . Then  $\omega=1+\alpha$  (see Remark 1.5) and by Example 1.9,  $\langle D \rangle=1$ . Hence

$$W(D) = 2^{-b_+} \cdot 2^{-b_-} \sum_{P \subset D} 1 = 2^{|D| - b_+ - b_-} = 2^{\operatorname{rk} H_1(\chi_D)}.$$

REMARK 1.11. Observe that if  $\omega$  is replaced in Theorem 1.3 throughout by  $\mu\omega$ , where  $\mu$  is a constant complex number, then another invariant is obtained. The new invariant is the old one multiplied by  $\mu^{\text{rk}\,H_1(\chi_D,\mathbb{Z})}$ . Choose  $\mu\in\mathbb{C}$  so that  $\mu^{-2}=f_{U_+}(\omega)\cdot f_{U_-}(\omega)$ . This means that  $f_{U_+}(\mu\omega)^{-1}=f_{U_-}(\mu\omega)$ . So we obtain the Witten invariant  $R(D)=f_D(\mu\omega,\mu\omega,\dots,\mu\omega)f_{U_-}(\mu\omega)^{\sigma}$ .

LEMMA 1.12. For the Kauffman bracket at  $a = e^{\pi i/6}$ , we have

$$\langle D \rangle = (-1)^{|D|_+} \cdot i^{\#D} = (-1)^{|D|_-} \cdot i^{-\#D} = i^{2|D|-D\cdot D}.$$

PROOF. First we prove that

$$\langle D \rangle = i \langle D_1 \rangle = -i \langle D_2 \rangle,$$

where the diagrams D,  $D_1$  and  $D_2$  differ as shown in Figures 2 (b)–(c). This can be verified by induction on #D. It follows from (a) that we must only prove that  $\langle D_1 \rangle = -\langle D_2 \rangle$ . The base #D = 0, 1 is easy. If  $\#D \ge 2$ , then  $D_1$  and  $D_2$  have a crossing point. The induction hypothesis then gives  $\langle D_1 \rangle = i \langle D_{11} \rangle = -i \langle D_{21} \rangle = -\langle D_2 \rangle$ , where the diagrams  $D_i$  and  $D_{i1}$  are identical except where shown in Figure 2 (b) (i = 1, 2) and (\*) is proved. From this at once we obtain the first two equalities of Lemma 1.12.

Now we prove that  $\langle D \rangle = i^{\,2|D|-D\cdot D}$ . The equality is evident for trivial diagrams D (that is, for diagrams without any crossings). By Proposition 1.2 it also holds for diagrams of the unoriented trivial link. There exists an orientation  $\overline{D} = (\overline{D}_1, \ldots, \overline{D}_k)$  of D such that  $b_{pq}$  equals the sum of the signs  $\pm 1$  of all the crossings where  $\overline{D}_p$  overcrosses  $\overline{D}_q$ . It is well known that D can be obtained from the diagram of the trivial link by changing some overcrossings by undercrossings and reverse operations. Clearly,  $i^{-D\cdot D}$  is multiplied by -1 under such operation. It follows from (\*) that  $\langle D \rangle$  is also multiplied by -1 and we are done.

EXAMPLE 1.13. Suppose r=3, k=1 and  $a=e^{\pi i/6}$ . Then  $\omega=1-\alpha$ ,  $f_{U_+}(\omega)=1-i$ ,  $f_{U_-}(\omega)=1+i$ ,  $\mu=1/\sqrt{2}$  and  $f_{U_-}(\mu\omega)=e^{\pi i/4}$ . Hence, by Lemma 1.12 the Witten invariant of Remark 1.11 equals

$$R(D) = 2^{-|D|/2} e^{\pi i \sigma/4} \sum_{P \subset D} (-1)^{|P|} \langle P \rangle = 2^{-|D|/2} e^{\pi i \sigma/4} \sum_{P \subset D} i^{-P \cdot P}.$$

Note that R(D) is obtained from  $\tau_3(D)$  of [4, page 521] by complex conjugation.

EXAMPLE 1.14. Let r=4, k=1 and  $a=e^{\pi i/8}$ . We have  $\omega=\alpha^2-\sqrt{2}\alpha$ ,  $\langle U_+^2\rangle=\langle U_-^2\rangle=0$ ,  $f_{U_+}(\omega)=-2e^{3\pi i/8}$ ,  $f_{U_-}(\omega)=2e^{5\pi i/8}$  and  $\mu=1/2$ . Therefore, the Witten invariant from Remark 1.11 equals

$$R(D) = (-1)^{|D|} 2^{-|D|/2} e^{5\pi i \sigma/8} \sum_{P \subset D} \left( -\sqrt{2} \right)^{-|P|} \langle D \circ P \rangle,$$

where  $D \circ P$  is the diagram obtained from D by drawing circles, parallel and close to the components of P, see for example [4, Section 6].

## 2. Simple proofs of Theorem 1.3 for r = 3 and r = 4

We only consider the case k = 1. The case of arbitrary k (for given r) is proved analogously.

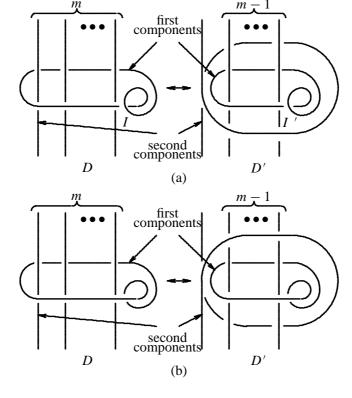


FIGURE 3.

LEMMA 2.1. The numbers  $b_+(D)$  and  $b_-(D)$  remain unchanged under the moves in Figures 3 (a)–(b).

**PROOF.** Let D and D' be the diagrams shown in Figures 3 (a)–(b). It is easy to see that  $(b_{pq}) = (x_{pq})^t (b'_{pq})(x_{pq})$  for  $x_{pp} = 1$ ,  $x_{12} = \pm 1$  and  $x_{pq} = 0$  otherwise, where the first two components of D and D' are specified. Hence the lemma follows.

It follows from Proposition 1.1 and Proposition 1.2 that for proving the invariance of W(D) one need only verify the invariance under the Fenn-Rourke moves in Figure 4 (a)–(b).

PROOF OF THEOREM 1.3 FOR r=3 AND k=1. Let  $a=e^{\pi i/6}$ . The proof is essentially the same as in [4, page 521], where invariance under the Kirby transformations was verified. It follows from Lemma 1.12 and Example 1.13 that

$$R(D) = 2^{-|D|/2} e^{\pi i \sigma/4} \sum_{P \subset D} (-1)^{|P|+|P|} i^{\#D} = 2^{-|D|/2} e^{\pi i \sigma/4} \sum_{P \subset D} (-1)^{|P|+|P|} i^{\#D}.$$

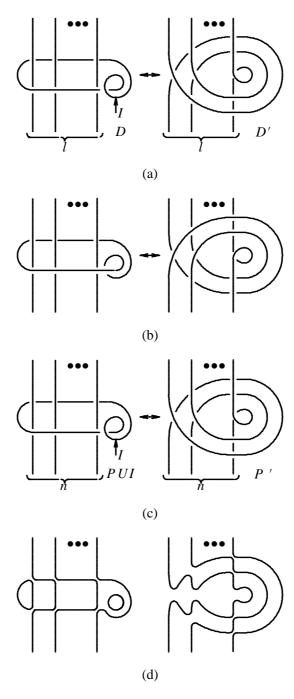


FIGURE 4.

We prove the invariance under the move in Figure 4 (a) using the formula for R(D) involving  $|\cdot|_+$ . The invariance under the move in Figure 4 (b) is verified analogously using the formula for R(D) involving  $|\cdot|_-$ . Denote by D, D', and I the diagrams shown in Figure 4 (a). Clearly, the Fenn-Rourke move in Figure 4 (a) is decomposed into I second Kirby moves in Figure 3 (a) (for  $m=l,\ldots,1$ ) and one first Kirby move in Figure 5. Since  $\sigma(D'\cup U_+)=\sigma(D')+1$ , it follows from Lemma 2.1 that  $\sigma(D)=\sigma(D')+1$ . Let P denote an arbitrary subdiagram of  $D\setminus I$ . Clearly,  $|P\cup I|=|P|+1$  and  $|P\cup I|_+=|P|+2$ . Hence, we have

$$\begin{split} R(D) &= \frac{2^{-|D'|/2} e^{\pi i \sigma(D')/4}}{1-i} \sum_{P \subset D \setminus I} \left( (-1)^{|P|+|P|_+} i^{\#P} + (-1)^{|P \cup I|+|P \cup I|_+} i^{\#(P \cup I)} \right) \\ &= 2^{-|D'|/2} e^{\pi i \sigma(D')/4} \sum_{P \subset D \setminus I} (-1)^{|P|+|P|_+} \frac{i^{\#P} + i^{\#(P \cup I)}}{1-i} \,. \end{split}$$

There exists a natural correspondence between the subdiagrams of D' and  $D \setminus I$ . If P' and P are the corresponding subdiagrams, then (by Figures 4 (c)–(d)), |P| = |P'|,  $|P|_+ = |P'|_+$ ,  $\#P = \#P' - n^2$ ,  $\#(P \cup I) = \#(P') - n^2 + 2n + 1$ , where  $n \ge 0$  is the number of components in the part of P corresponding to the part of P shown in Figure 4 (a). Since  $i^{-n^2} - i^{-n^2+2n+1} = 1 - i$ , it follows that R(D') = R(D).

LEMMA 2.2. W(D) remains unchanged under the first Kirby move in Figure 5.

PROOF. Clearly, 
$$b_{\pm}(D \cup U_{\pm}) = b_{\pm}(D) + 1$$
,  $b_{\pm}(D \cup U_{\mp}) = b_{\pm}(D)$ , and  $f_{D \cup U_{\pm}}(\omega, \dots, \omega) = f_{D}(\omega, \dots, \omega) \cdot f_{U_{\pm}}(\omega)$ .

Hence 
$$W(D \cup U_{-}) = W(D) = W(D \cup U_{+}).$$

LEMMA 2.3. W(E) remains unchanged under the Fenn-Rourke moves of the diagram E in Figures 4 (a)–(b) if for arbitrary diagrams D and D' that differ as in Figures 3 (a)–(b) the following equality holds

$$f_D(\omega, \alpha, \alpha, \ldots, \alpha) = f_{D'}(\omega, \alpha, \alpha, \ldots, \alpha).$$

PROOF. Clearly, the Fenn-Rourke moves in Figures 4 (a)–(b) are decomposed into l second Kirby moves in Figures 3 (a)–(b) (for  $m=l,\ldots,1$ ) respectively, and one first Kirby move in Figure 5. Thus it follows from Lemma 2.1 and Lemma 2.2 that we only need to check the equality  $f_D(\omega,\ldots,\omega)=f_{D'}(\omega,\ldots,\omega)$ , where D and D' are shown in Figure 3 (a) or 3 (b) and their first two components are specified. Let n=|D|=|D'| and  $k_2,k_3,\ldots,k_n\geq0$  be arbitrary integers. It suffices to verify that

$$f_D(\omega, \alpha^{k_2}, \alpha^{k_3}, \dots, \alpha^{k_n}) = f_{D'}(\omega, \alpha^{k_2}, \alpha^{k_3}, \dots, \alpha^{k_n}).$$

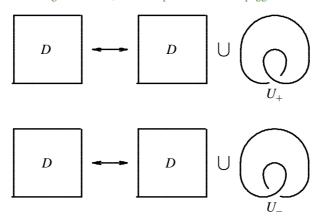


FIGURE 5.

This equality is clear for  $k_2=0$ . If  $k_i=0$ , for some  $i\geq 3$ , we may consider  $D\setminus D_i$  and  $D'\setminus D'_i$  instead of D and D'. Therefore we may assume that  $k_3,\ldots,k_n\neq 0$ . Let C and C' be the diagrams obtained from D and D' by taking  $k_i$  curves, for each  $i\geq 3$ , close and parallel to the i-th component. Considering C and C' instead of D and D' we may assume that  $k_3,\ldots,k_n=1$ . By induction on  $k_2$  it follows that the above equality for  $k_2=1$  implies the analogous equation for arbitrary  $k_2$ . Indeed, suppose that  $k_2\geq 2$ . Let  $K=D'^{(1,2,1,\ldots,1)}$  with |K|=n+1 and J' be the second component of D'. Obviously, we have  $D'^{(k_1,k_2,1,\ldots,1)}=K'^{(k_1,k_2-1,1,1,\ldots,1)}$ . The induction hypothesis for diagrams K and  $D\cup J'$  then gives that

$$f_{D'}(\omega, \alpha^{k_2}, \alpha, \dots, \alpha) = f_K(\omega, \alpha^{k_2 - 1}, \alpha, \alpha, \dots, \alpha)$$

$$= f_{D \cup J'}(\omega, \alpha^{k_2 - 1}, \alpha, \alpha, \dots, \alpha)$$

$$= f_D(\omega, \alpha^{k_2}, \alpha, \dots, \alpha).$$

PROOF OF THEOREM 1.3 FOR r=4 AND k=1. From now on assume that the Kauffman bracket is calculated at  $a=e^{\pi i/8}$ . We prove the invariance of W(D) under the move in Figure 4 (a). The invariance under the move in Figure 4 (b) is verified analogously. Let D and D' be the diagrams shown in Figure 3 (a). By I and I' we denote their first components.

Since  $\omega = \alpha^2 - \sqrt{2}\alpha$  it follows by Lemma 2.3 that we must only show that

$$(**) \qquad \langle D \circ I \rangle - \sqrt{2} \langle D \rangle = \langle D' \circ I' \rangle - \sqrt{2} \langle D' \rangle.$$

Applying (a) to the crossings marked in Figure 6 (a), we obtain  $-\sqrt{2}\langle D\rangle = \sqrt{2}a^3\langle S\rangle$ ,  $\langle D \circ I \rangle = 2\langle Q \rangle - \langle T \rangle$ ,  $-\sqrt{2}\langle D' \rangle = -\sqrt{2}\langle S' \rangle$  and  $\langle D' \circ I' \rangle = -2a^{-3}\langle Q' \rangle + a^{-3}\langle T' \rangle$ .

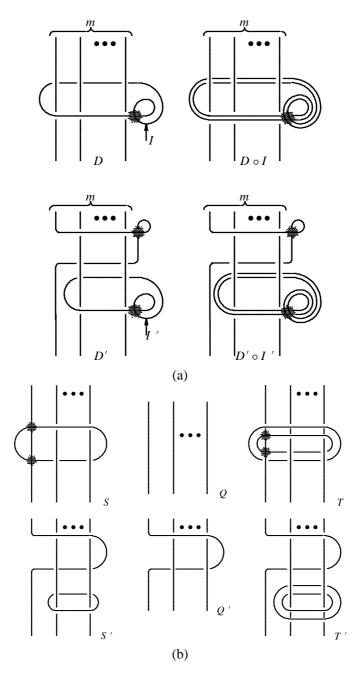


FIGURE 6.

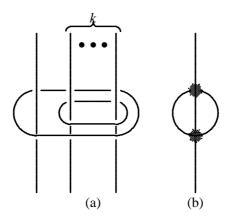


FIGURE 7.

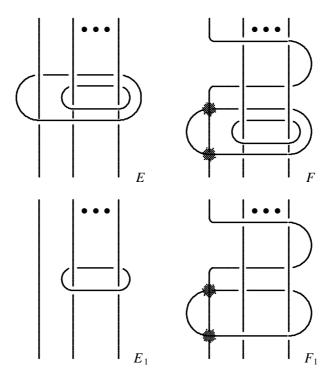


FIGURE 8.

To complete the proof of Theorem 1.3 for r = 4 and k = 1 we need the following simple lemma.

LEMMA 2.4. Suppose that the diagram A contains the part shown in Figure 7 (a), where  $k \ge 0$ . Then  $\langle A \rangle = 0$ .

**PROOF.** By property (a) of the Kauffman bracket, we may assume that A has no crossings outside the part shown. It is easy to see that A contains the part shown in Figure 7 (b). Applying (a) to the two marked crossings in Figure 7 (b) and using (b) one can easily obtain that  $\langle A \rangle = 0$ .

Applying (a) to the crossings of T and  $F_1$  marked in Figure 6 (b) and Figure 8, using Proposition 1.2 (for the first and the last equalities) and Lemma 2.4 (for the second equality) we get that

$$\langle T \rangle = (1+i)\langle F_1 \rangle + \frac{1+i}{\sqrt{2}}\langle E \rangle = (1+i)\langle F_1 \rangle = 2\langle Q \rangle + \sqrt{2}\langle S' \rangle.$$

Hence,  $\langle D \circ I \rangle - \sqrt{2} \langle D \rangle = \sqrt{2} a^3 \langle S \rangle - \sqrt{2} \langle S' \rangle$ . Clearly, (\*\*) is equivalent to the equality  $\sqrt{2} a^3 \langle S \rangle = -2 a^{-3} \langle Q' \rangle + a^{-3} \langle T' \rangle$ . Using Lemma 2.4 (for first equality), applying (a) to the crossings of F and S marked in Figure 6 (b) and Figure 8 and using Proposition 1.2 (for the last two equalities) we obtain that

$$\sqrt{2}a^{3}\langle S \rangle = \sqrt{2}a^{3}\langle S \rangle + a^{-1}\langle F \rangle$$

$$= \sqrt{2}a^{3}\langle S \rangle + a^{-3}\langle T' \rangle + \sqrt{2}a^{-3}\langle E_{1} \rangle$$

$$= -2a^{-3}\langle Q' \rangle + a^{-3}\langle T' \rangle$$

and we are done.

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Department of Differential Geometry Faculty of Mechanics and Mathematics Moscow State University Moscow 119899 Russia

e-mail: rafikov@mccme.ru

Institute for Mathematics,
Physics and Mechanics
University of Ljubljana
P.O. Box 2964
1001 Ljubljana
Slovenia

e-mail: dusan.repovs@fmf.uni-lj.si

Department of Mathematics University of Modena and Reggio Emilia Via Campi 213/B 41100 Modena Italy

e-mail: spaggiari@unimo.it